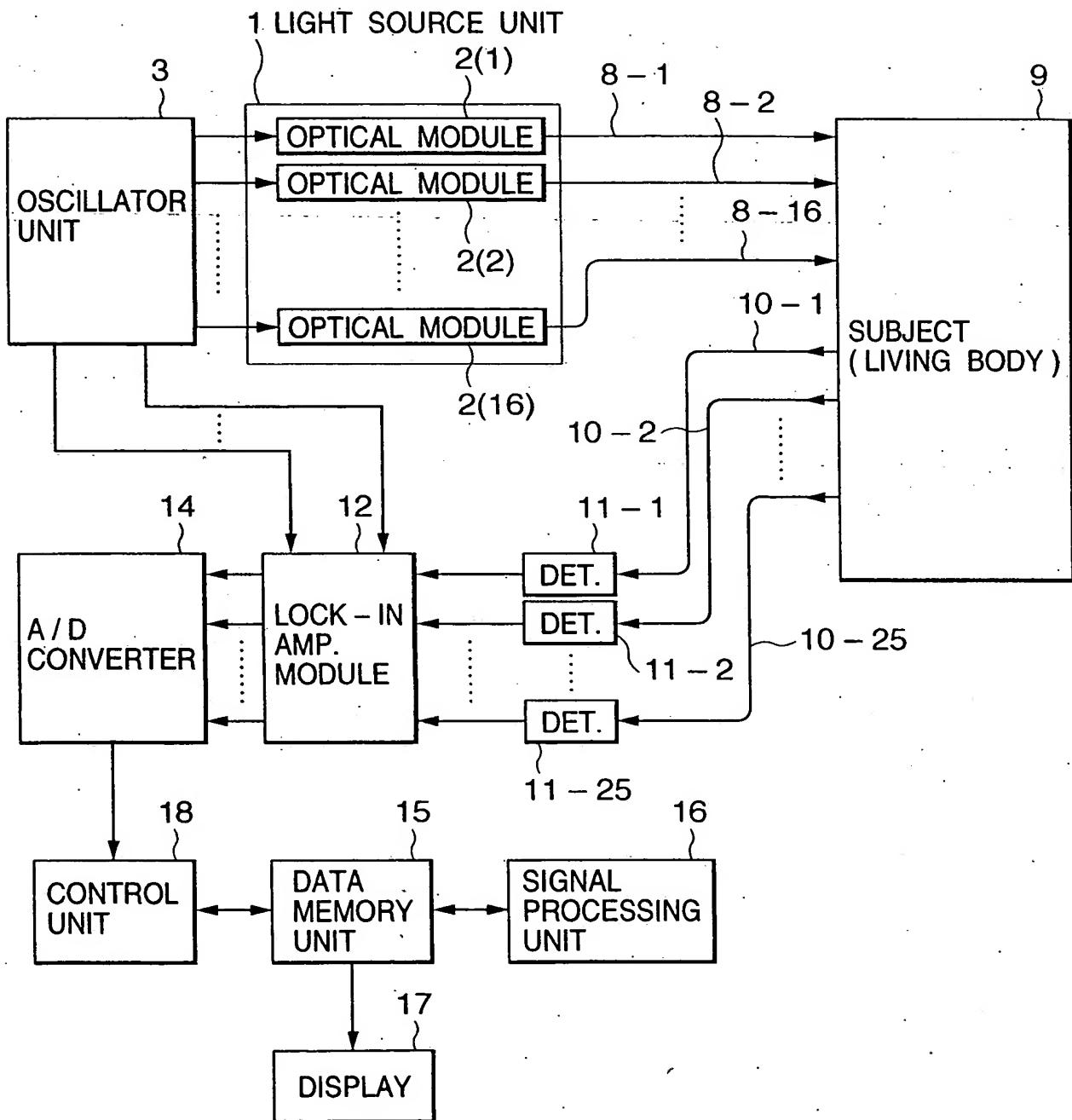


FIG. 1



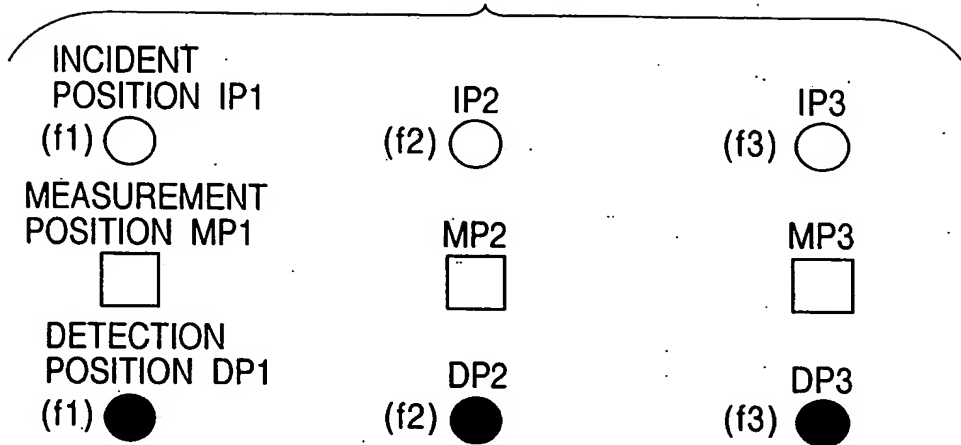
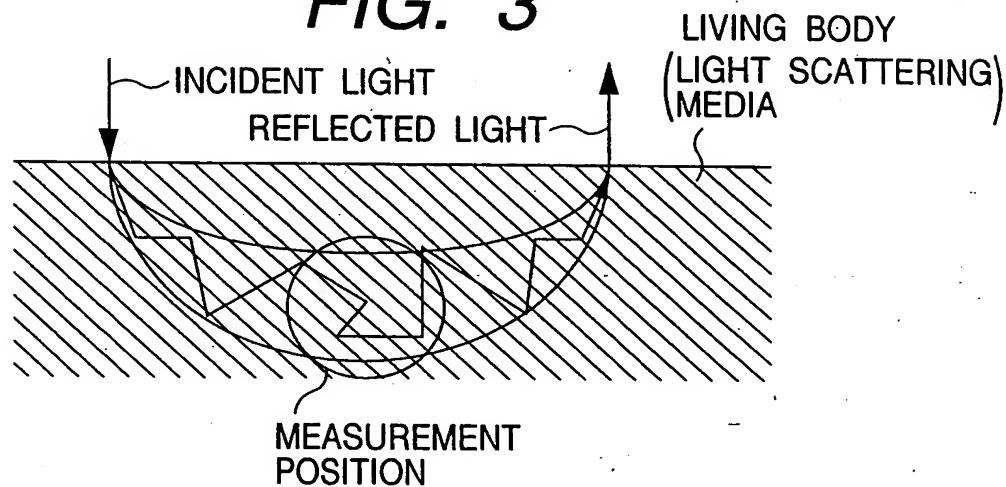
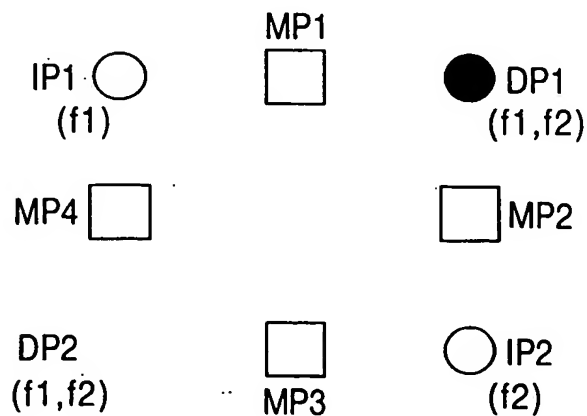
**FIG. 2****FIG. 3****FIG. 4**

FIG. 5

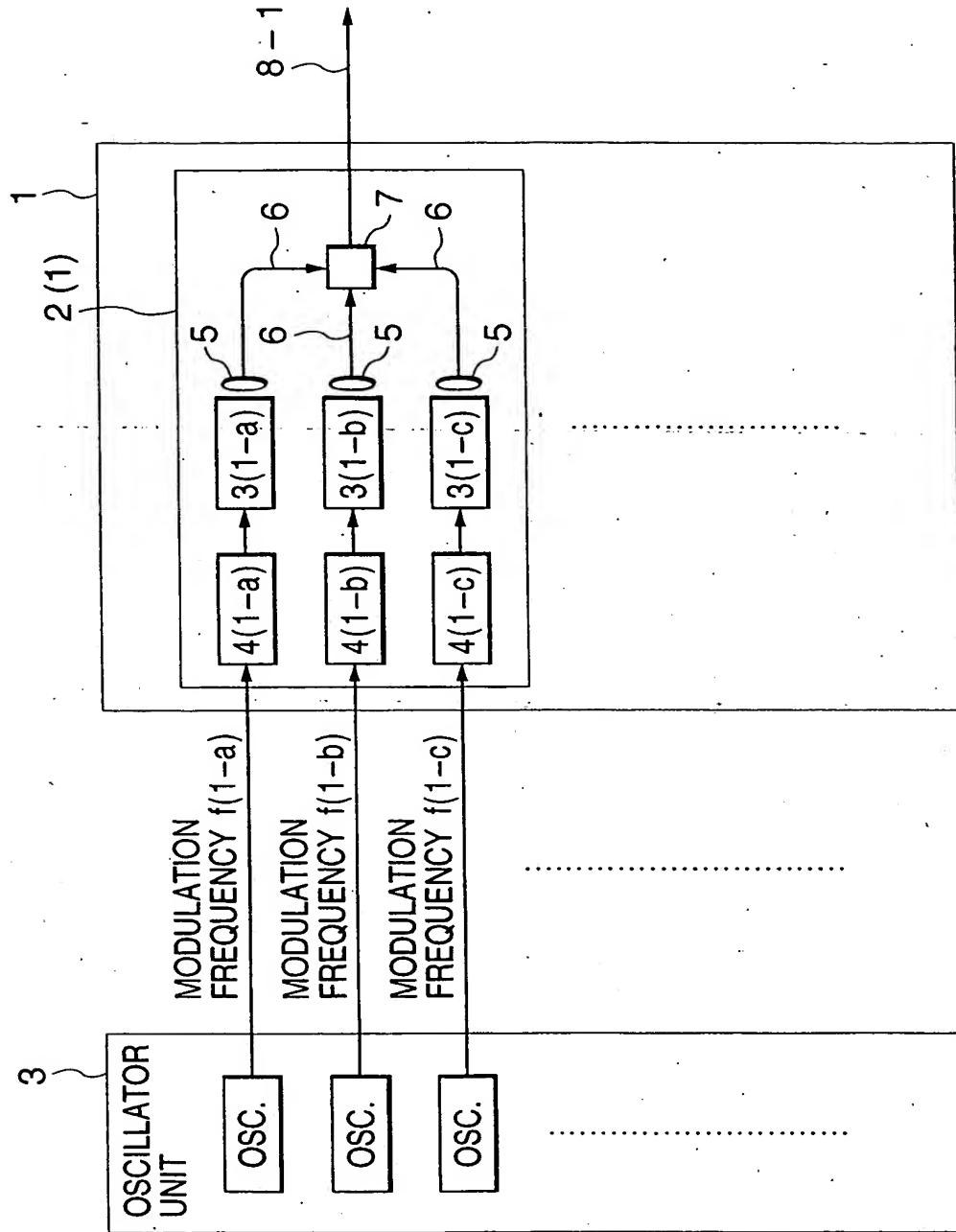
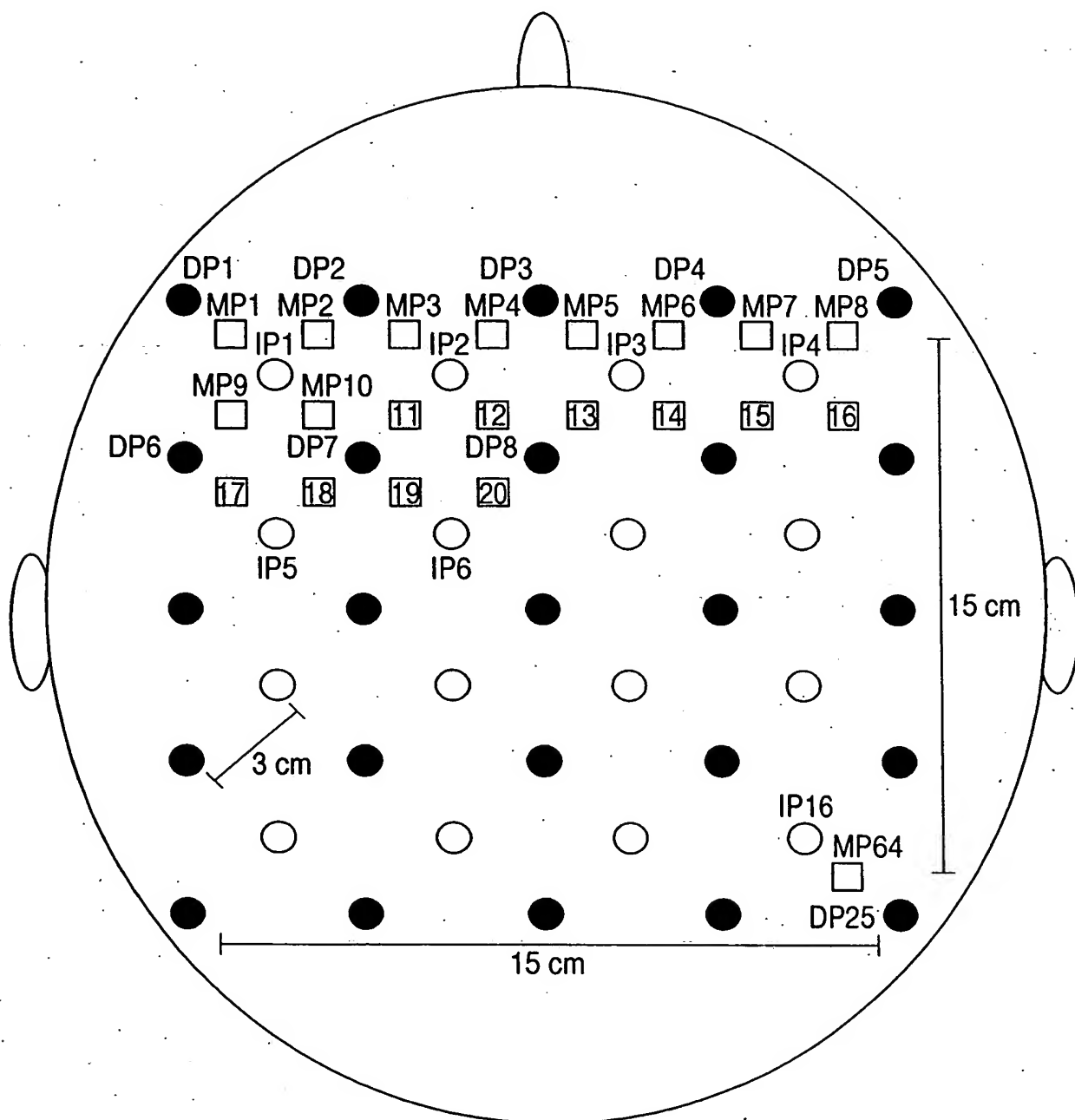
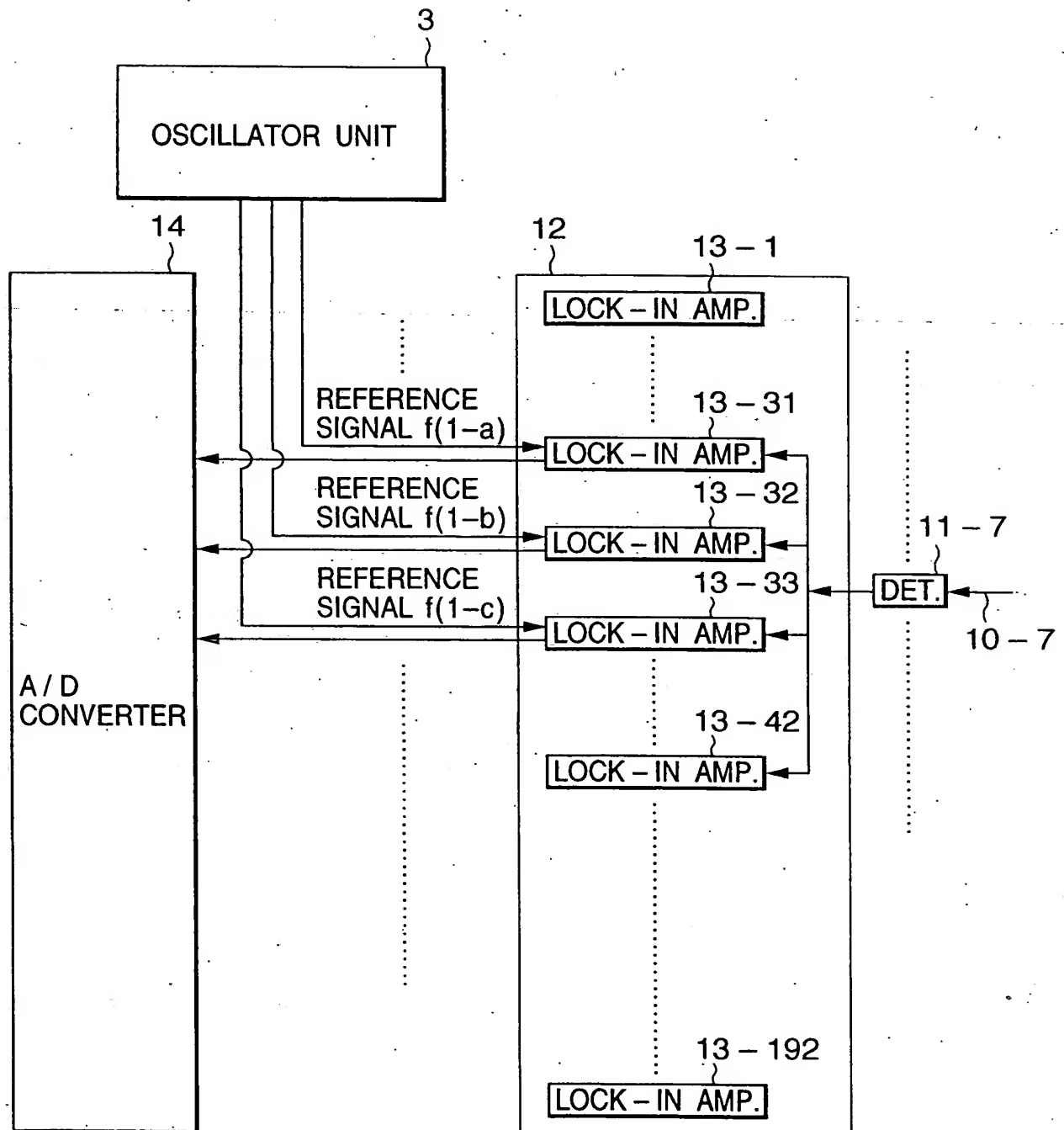


FIG. 6

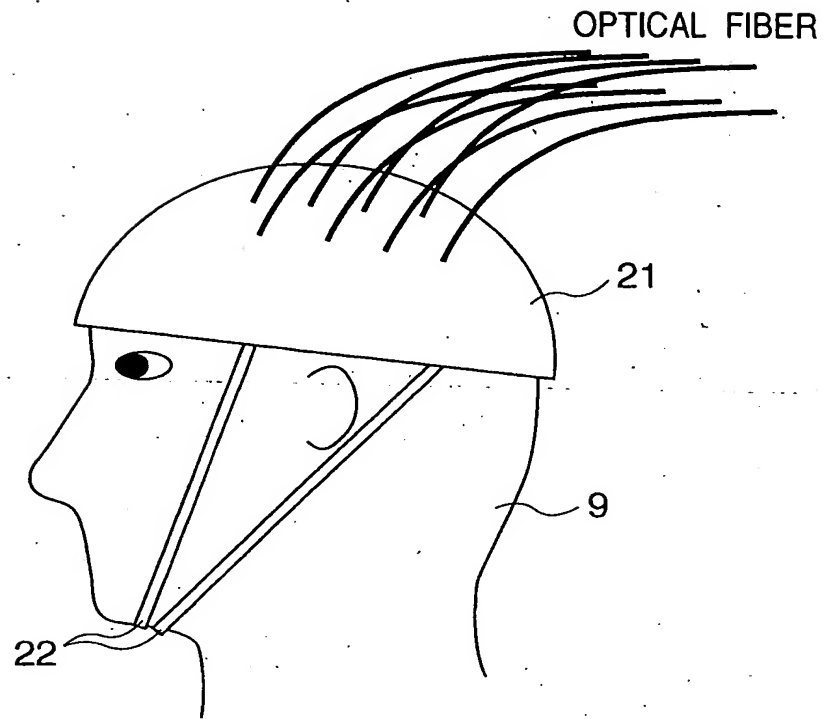


○ INCIDENT POSITION (IP)      ● DETECTION POSITION (DP)  
 □ MEASUREMENT POSITION (MP)

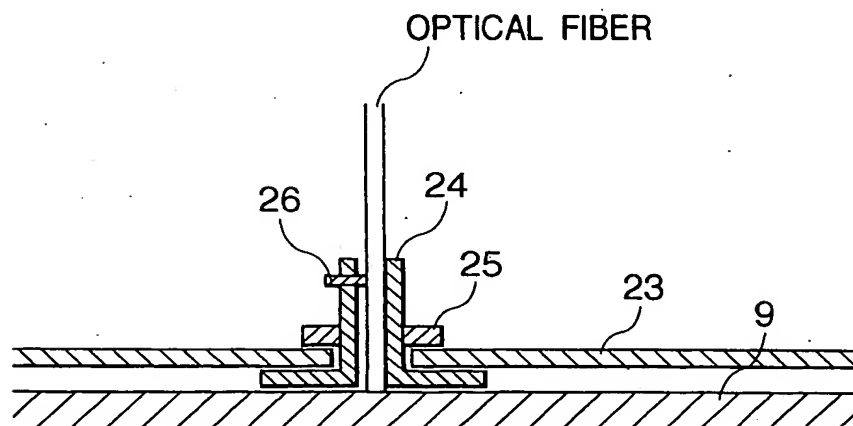
FIG. 7



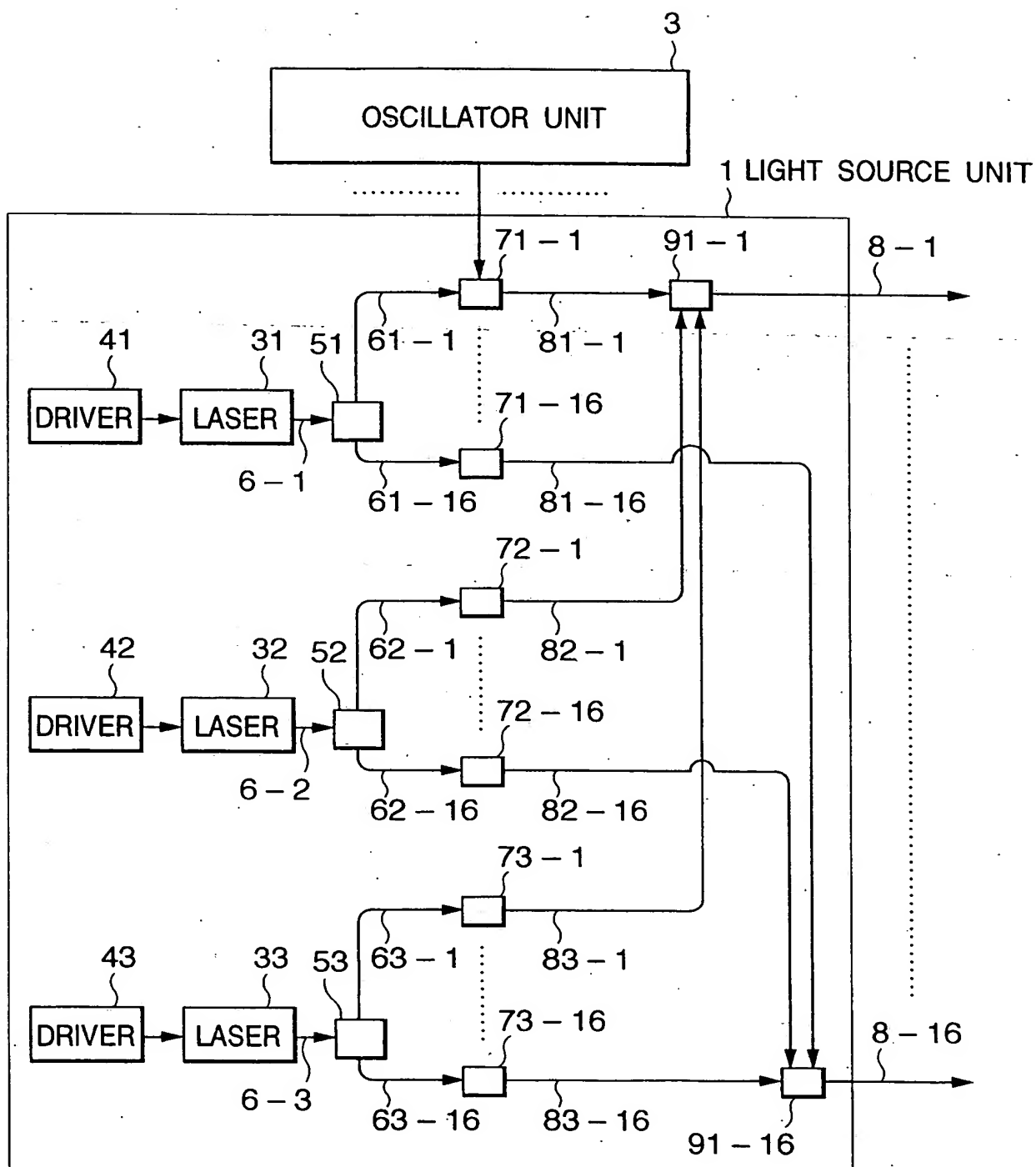
**FIG. 8**

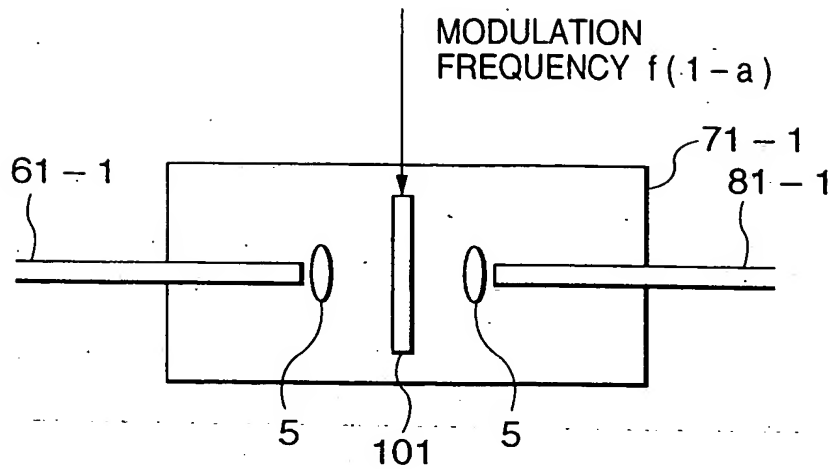
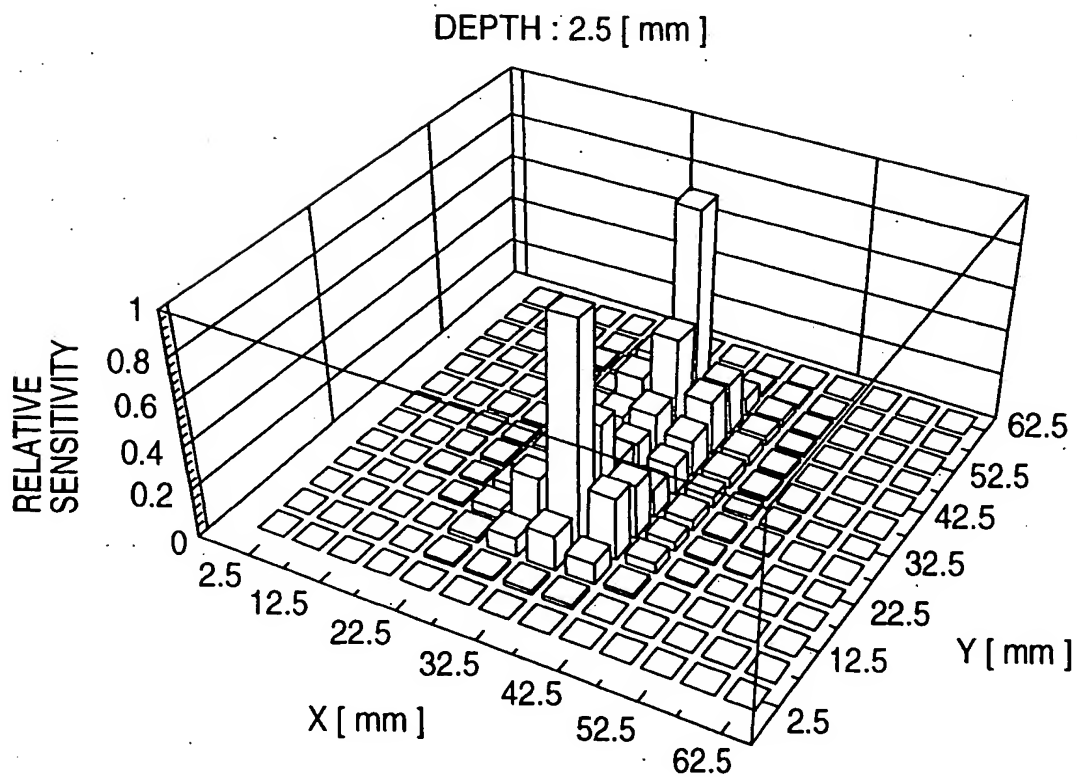


**FIG. 9**



**FIG. 10**



**FIG. 11****FIG. 12**



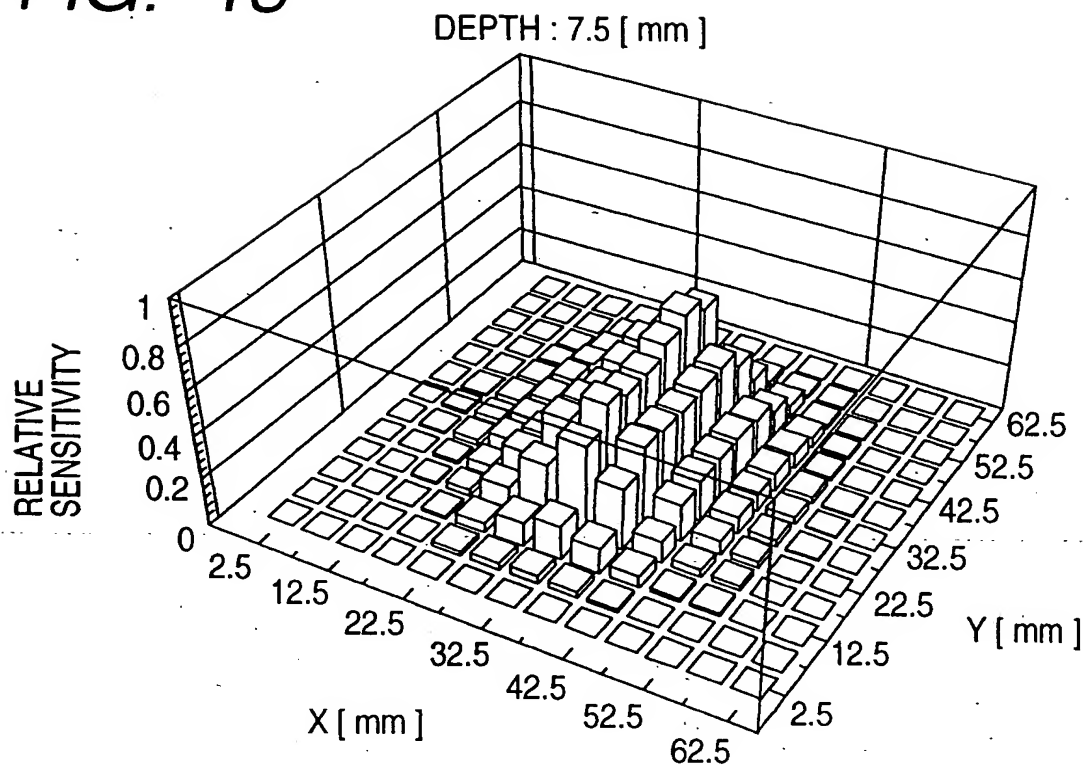
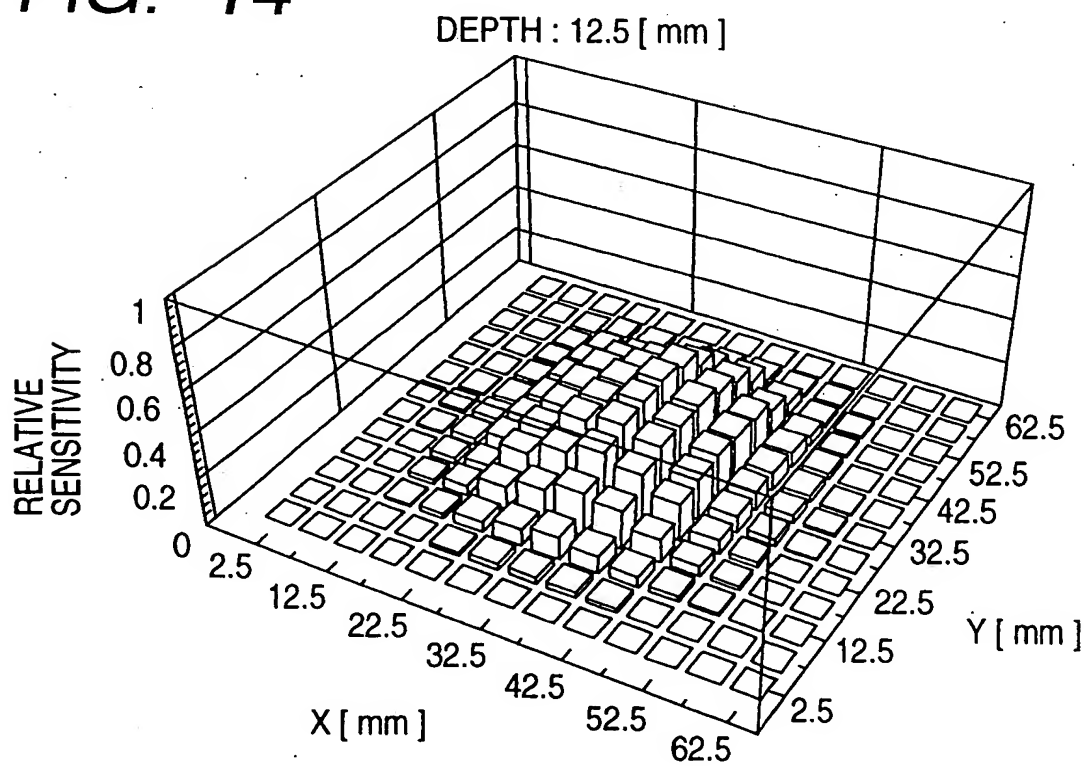
**FIG. 13****FIG. 14**

FIG. 15

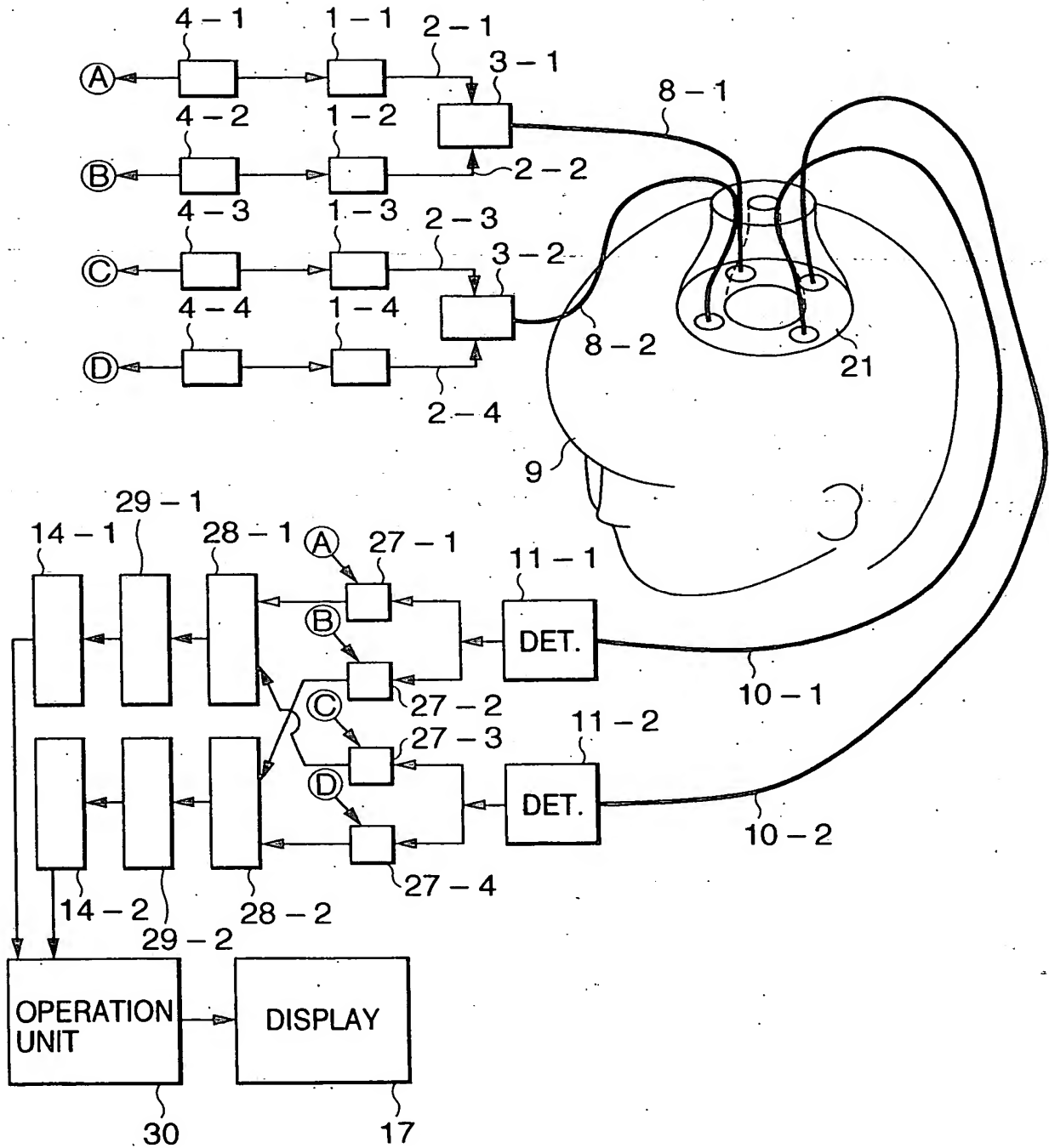


FIG. 16

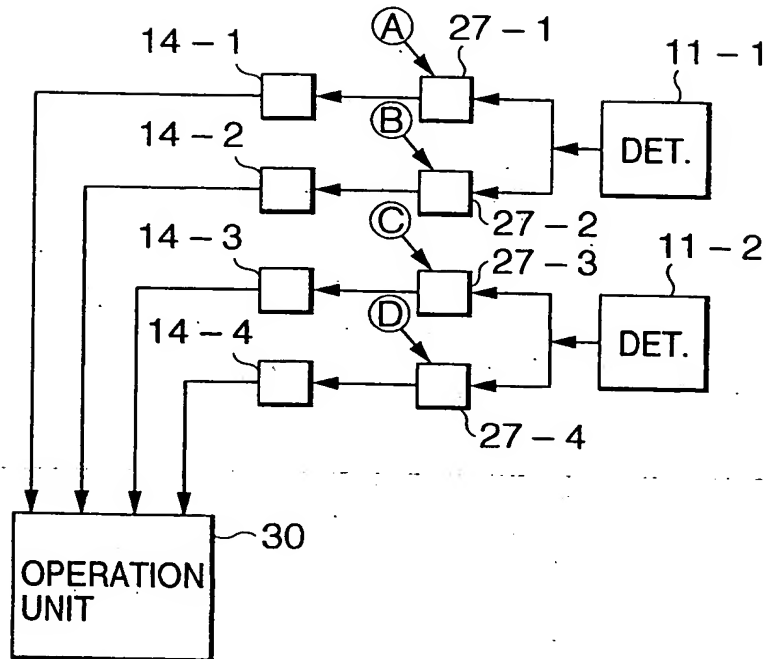


FIG. 17

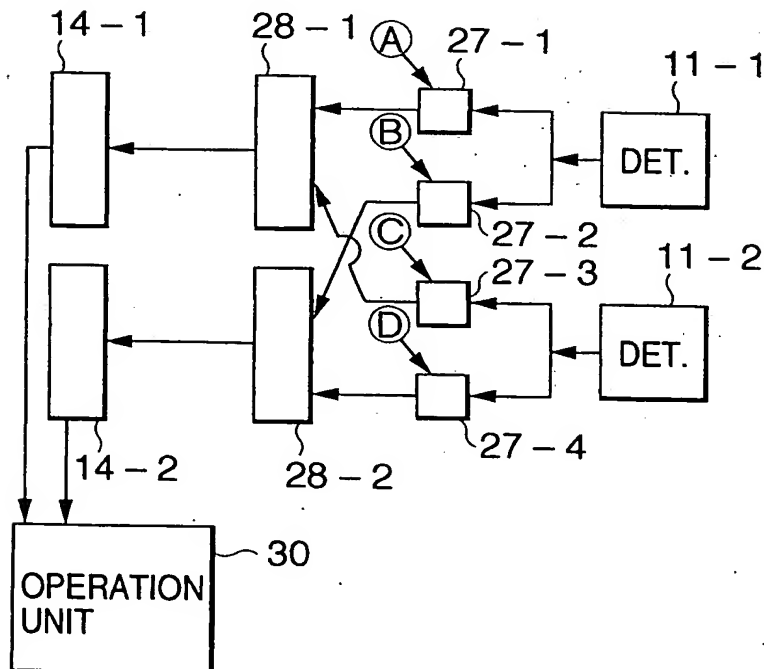


FIG. 18

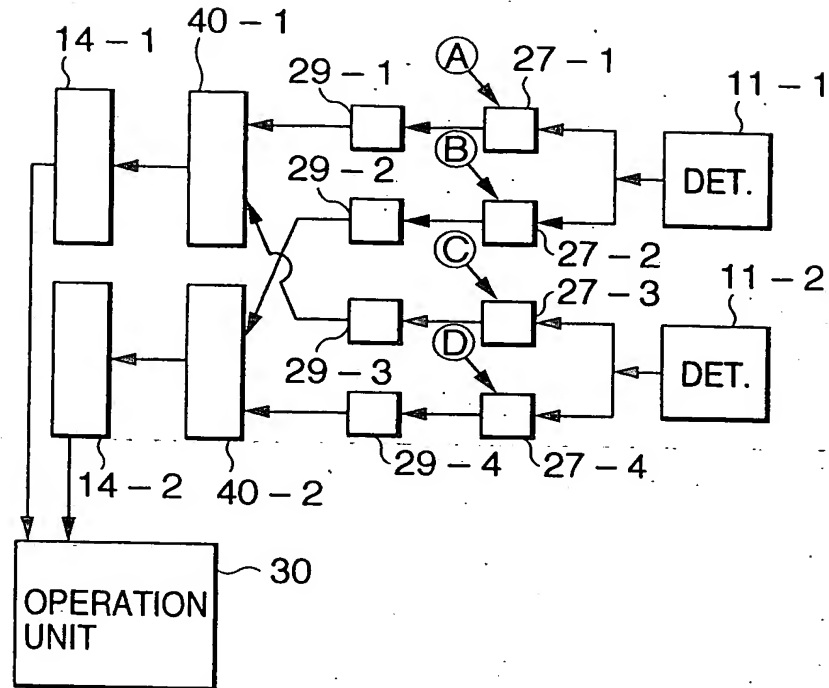
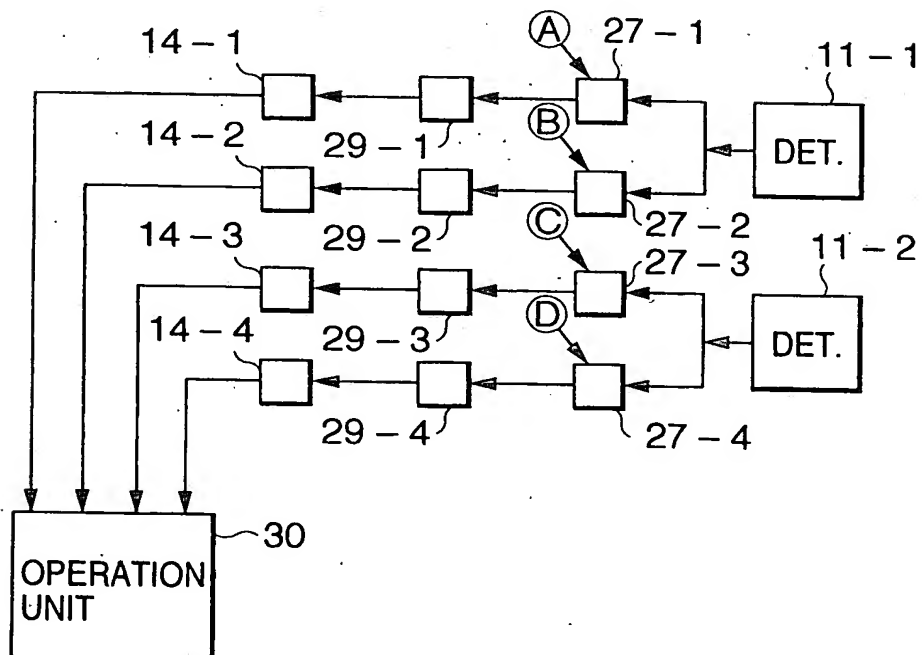
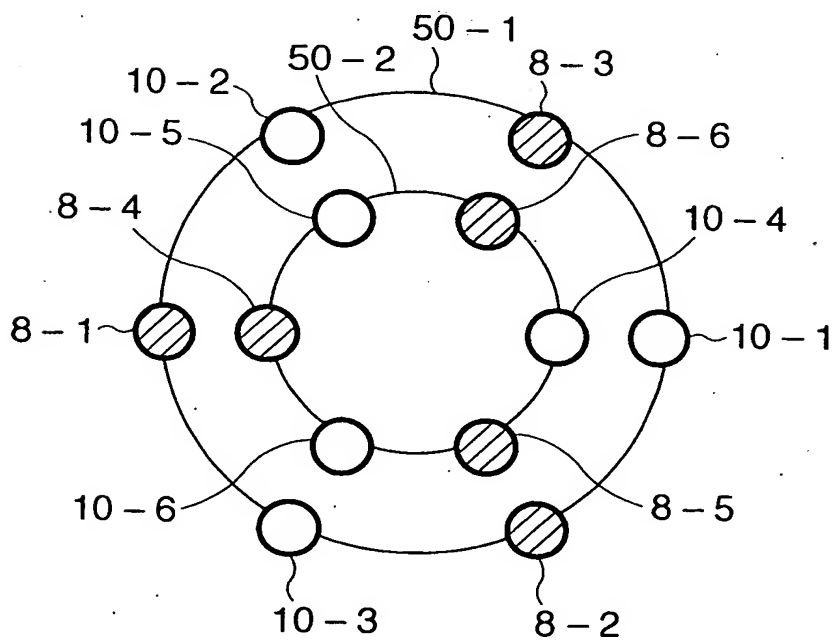
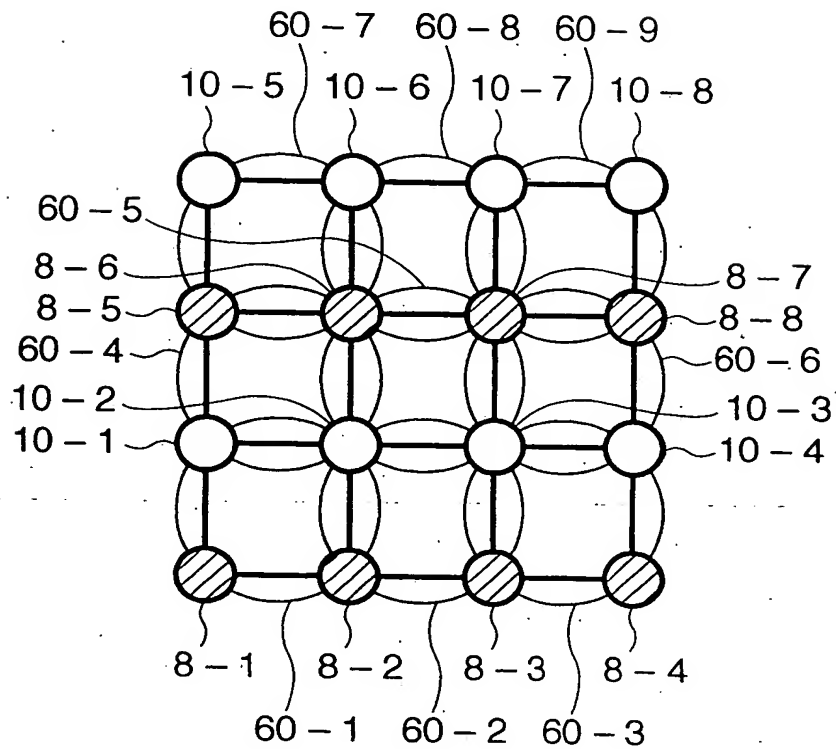
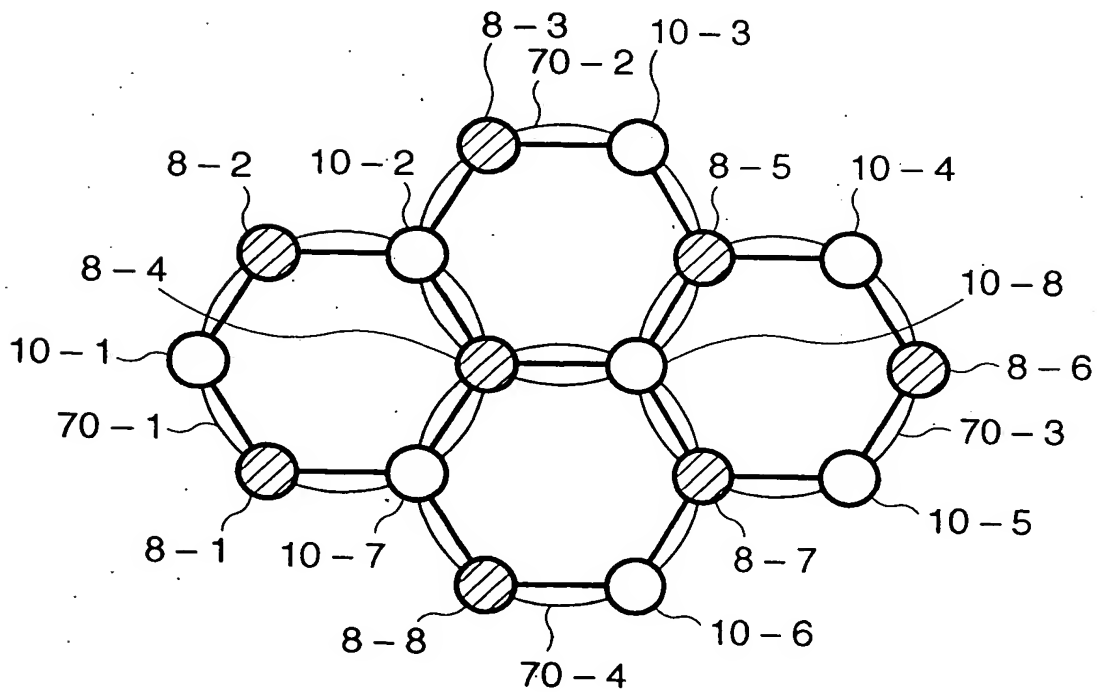


FIG. 19





**FIG. 22****FIG. 23**

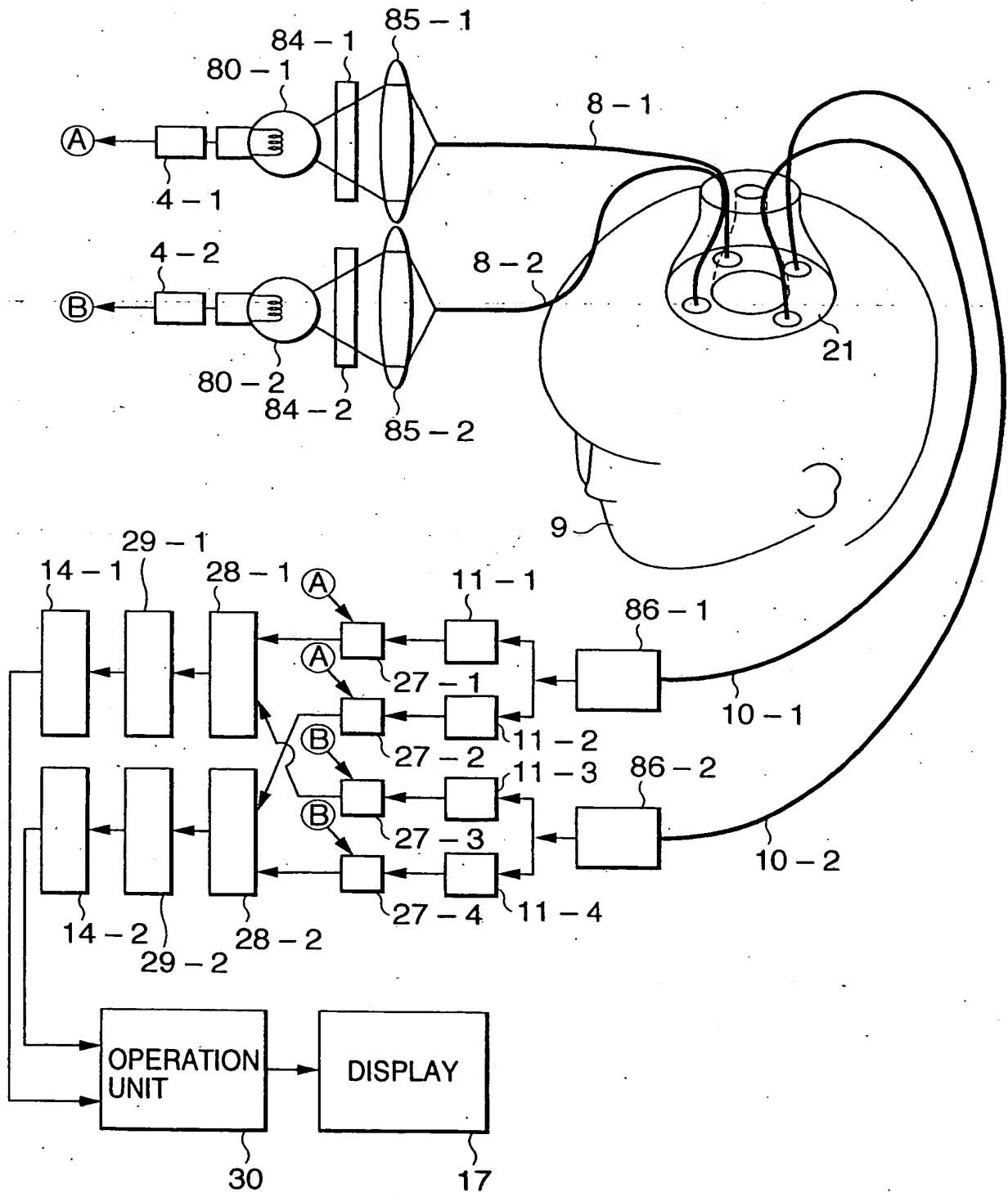


FIG. 25

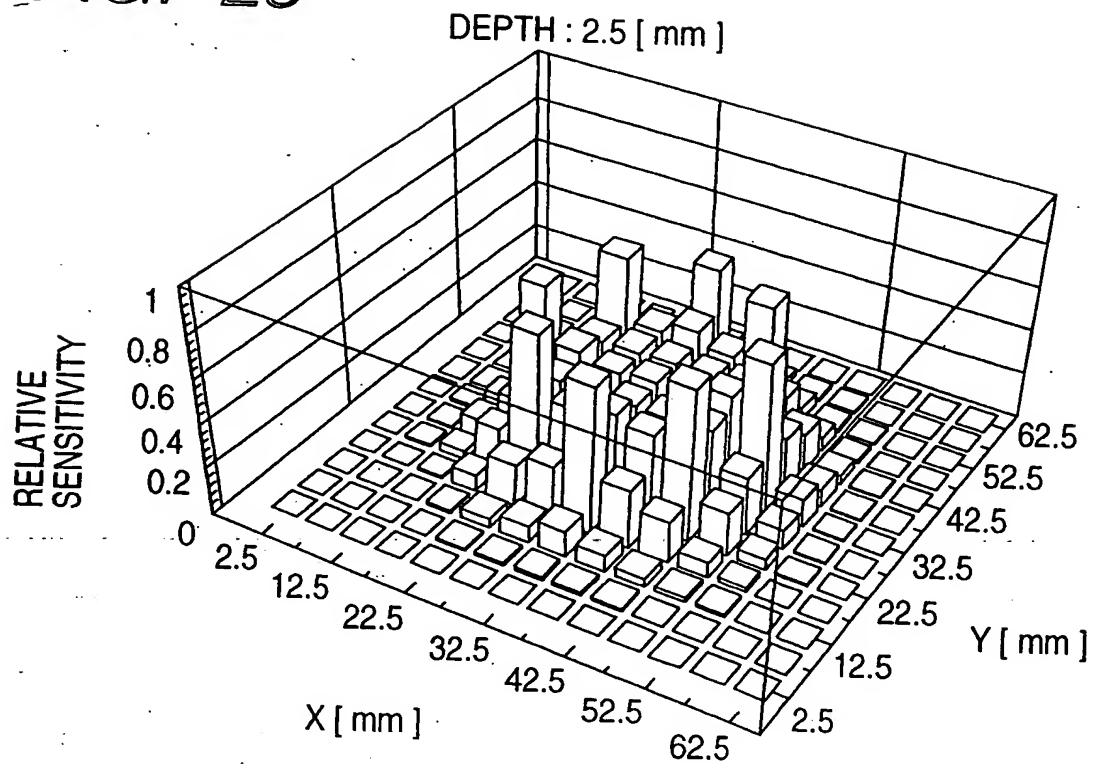
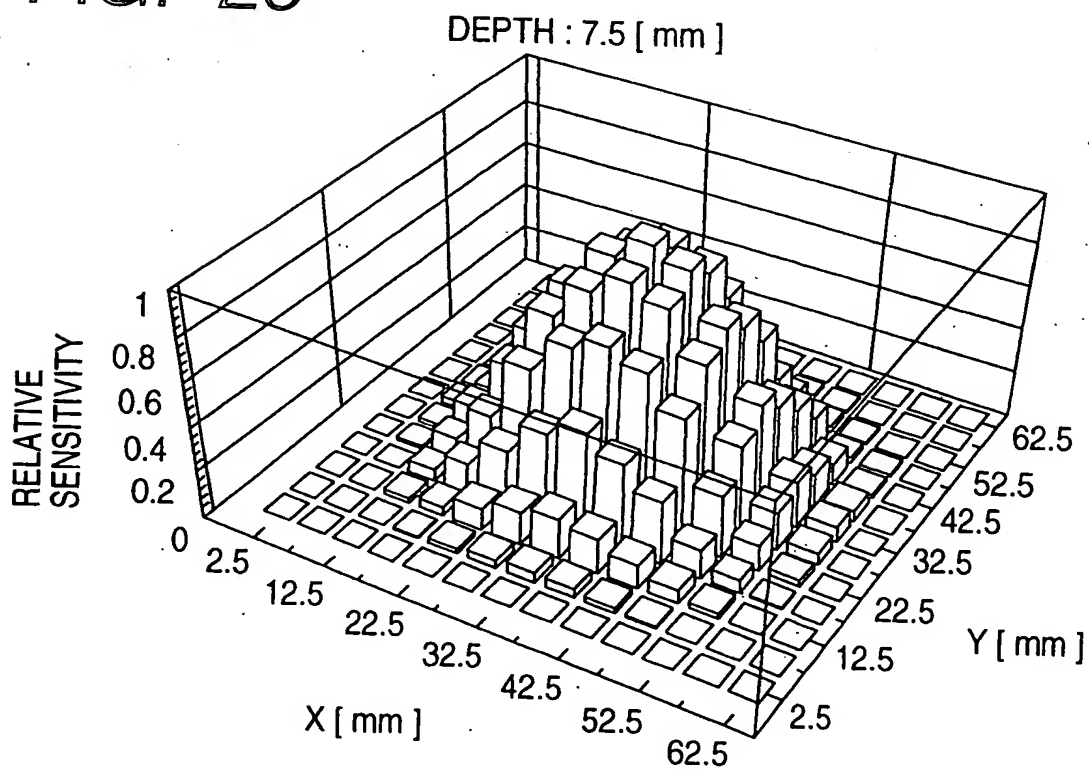


FIG. 26





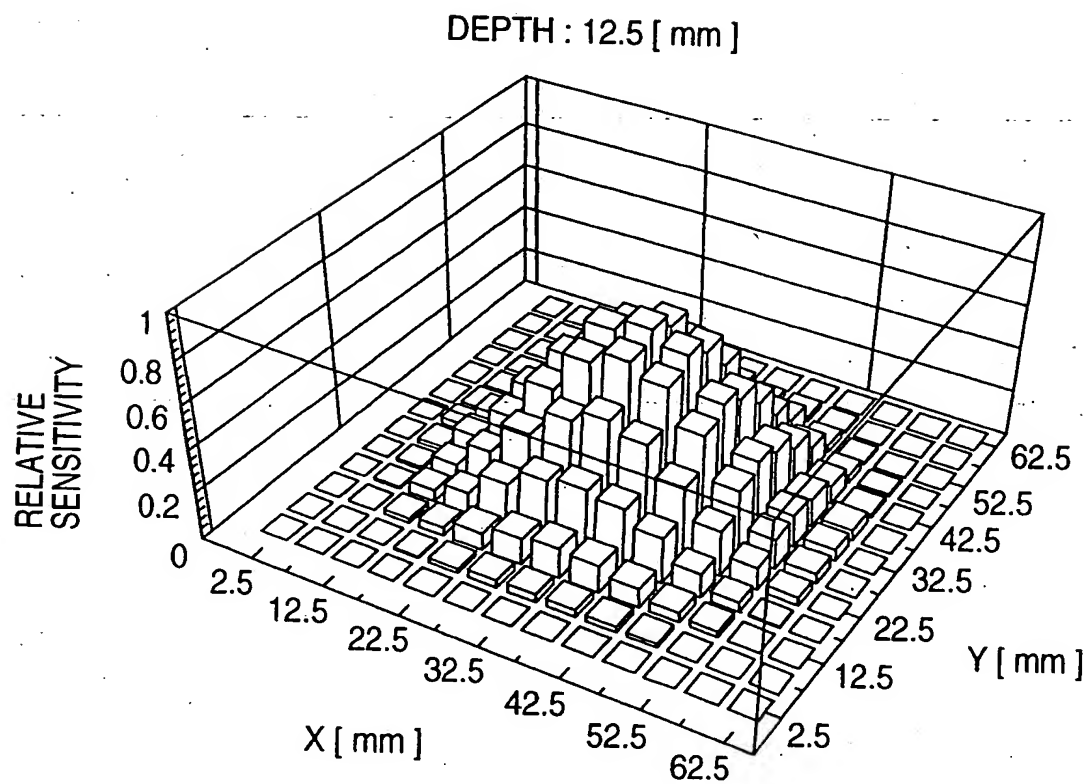
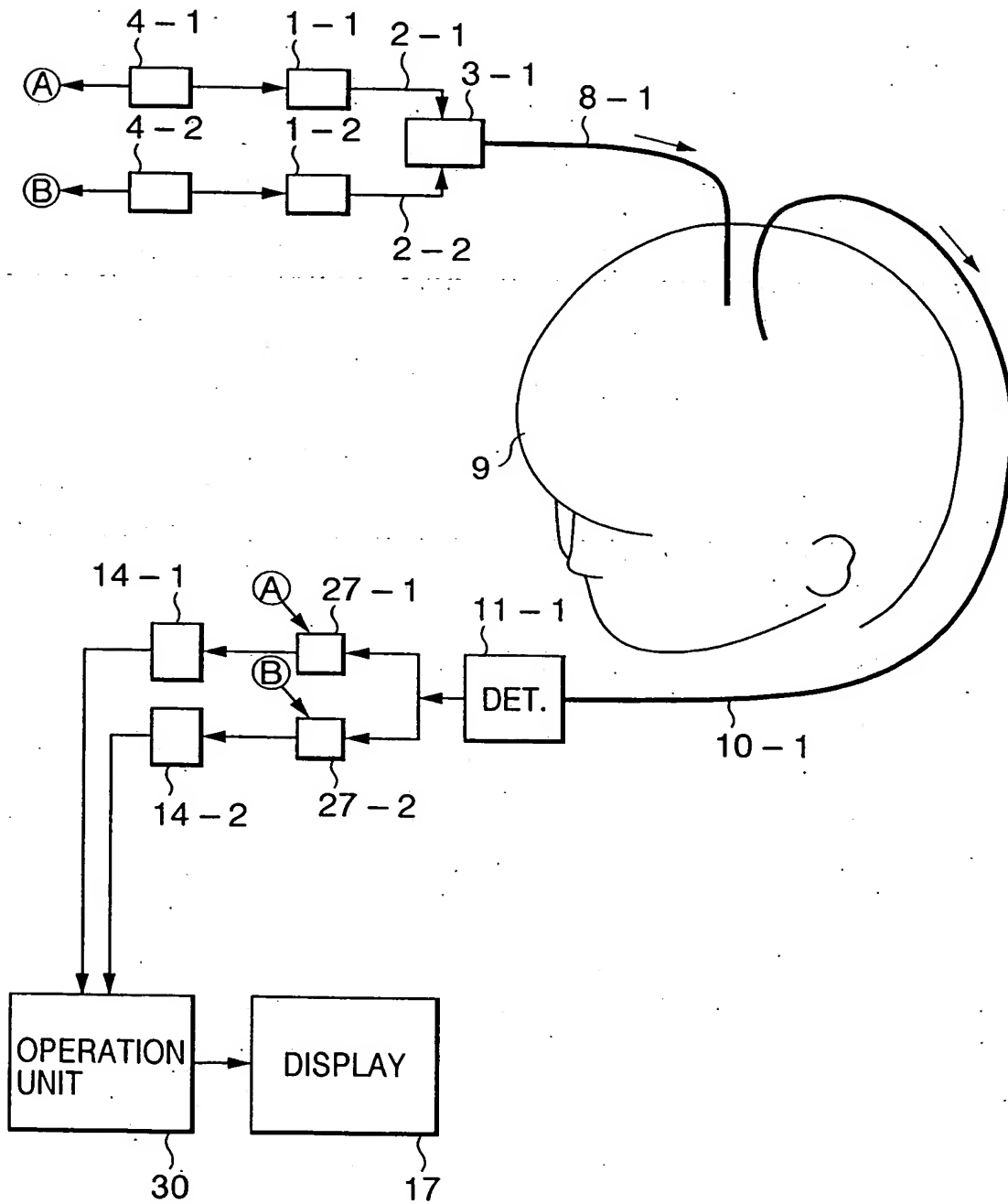
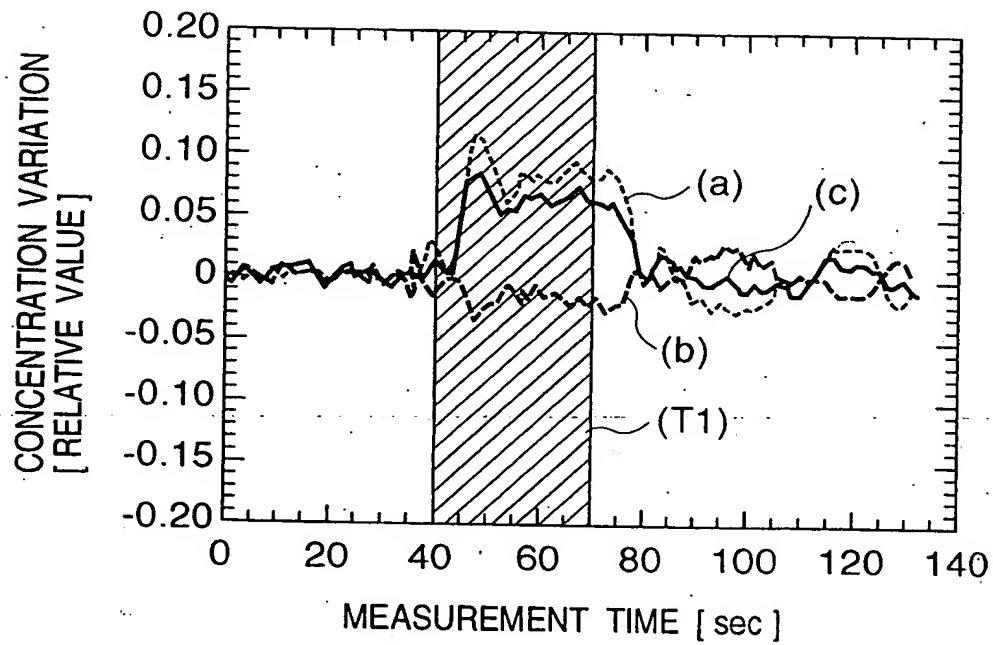
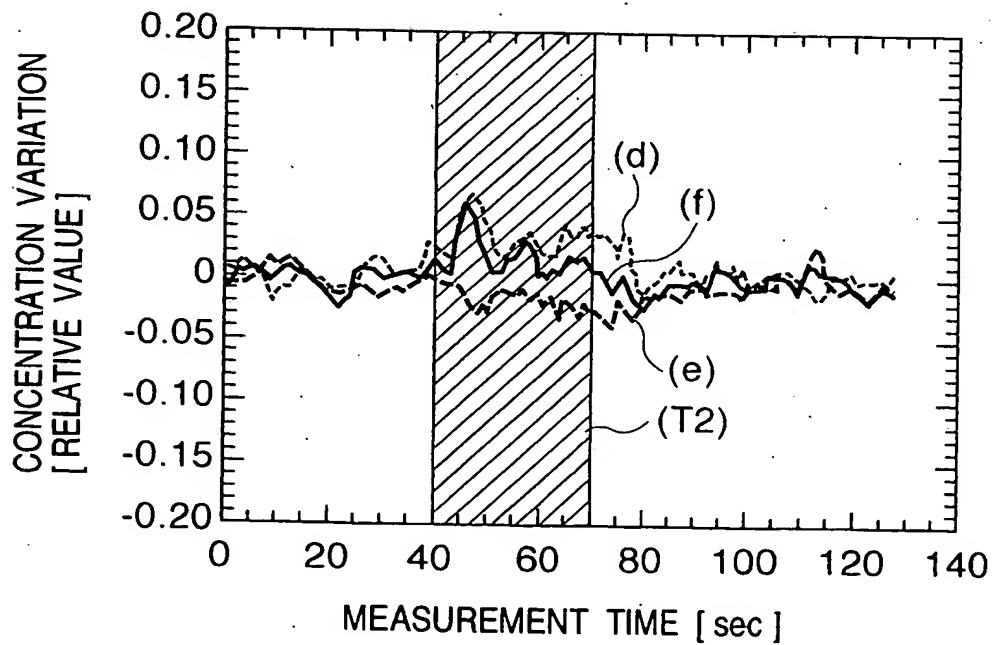
*FIG. 27*

FIG. 28



*FIG. 29**FIG. 30*

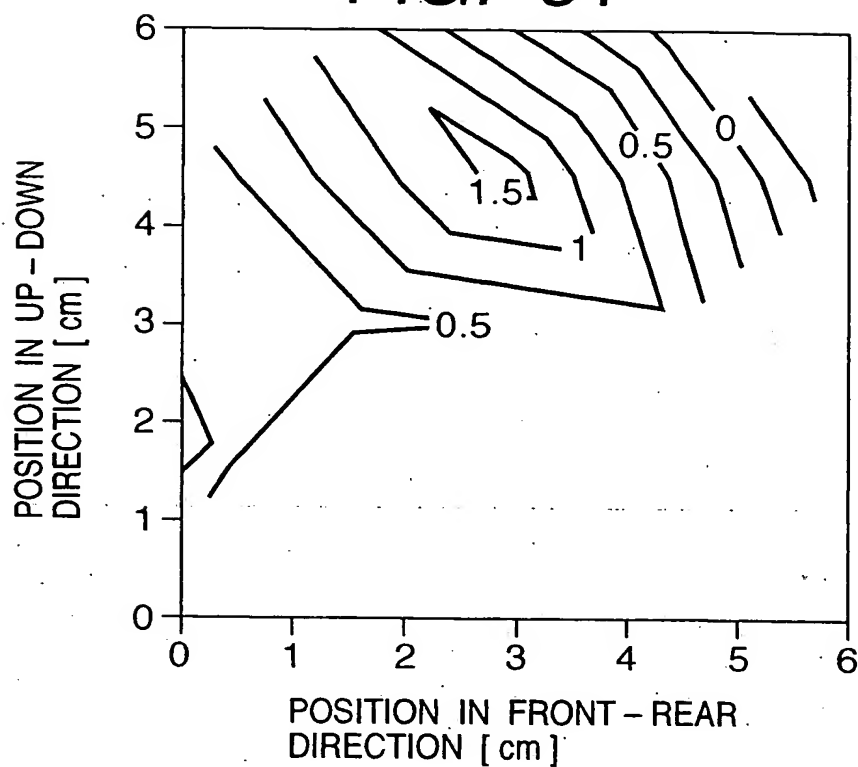
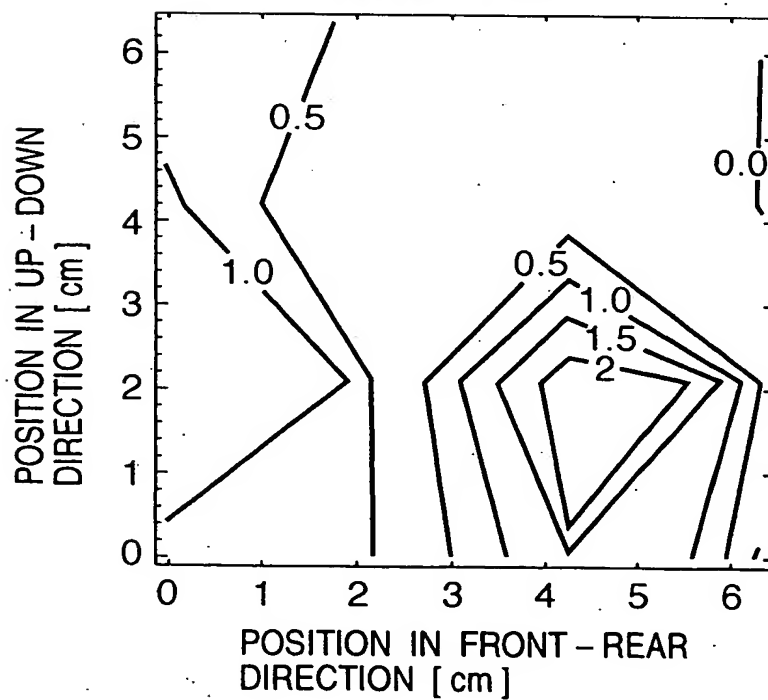
**FIG. 31****FIG. 32**

FIG. 33

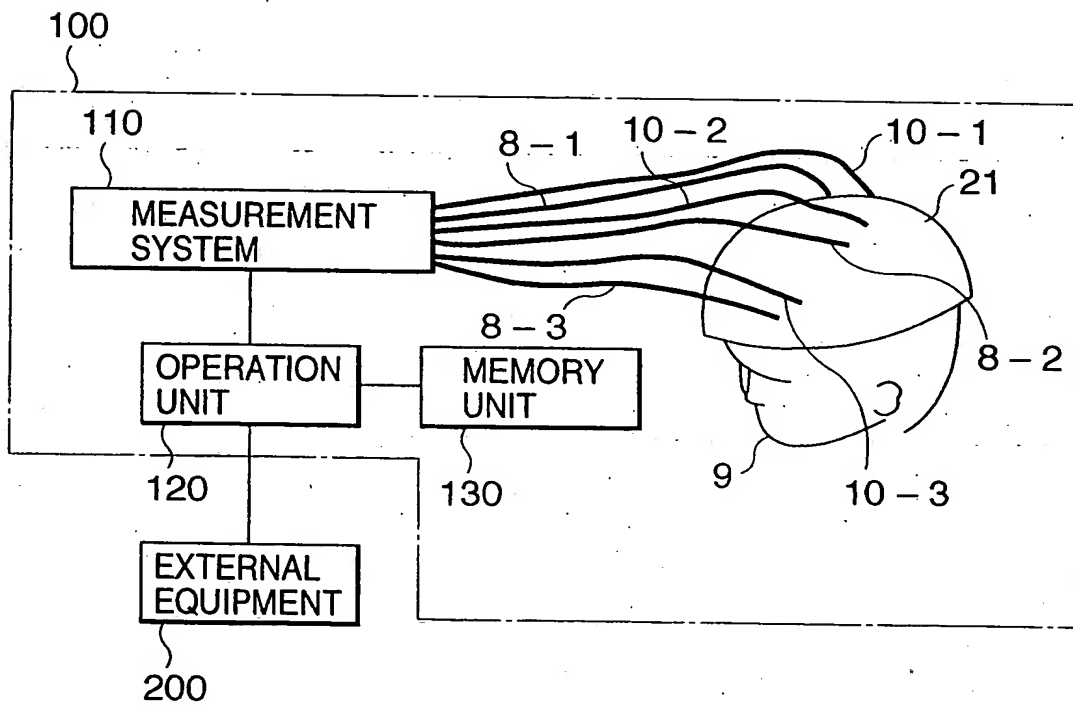


FIG. 34

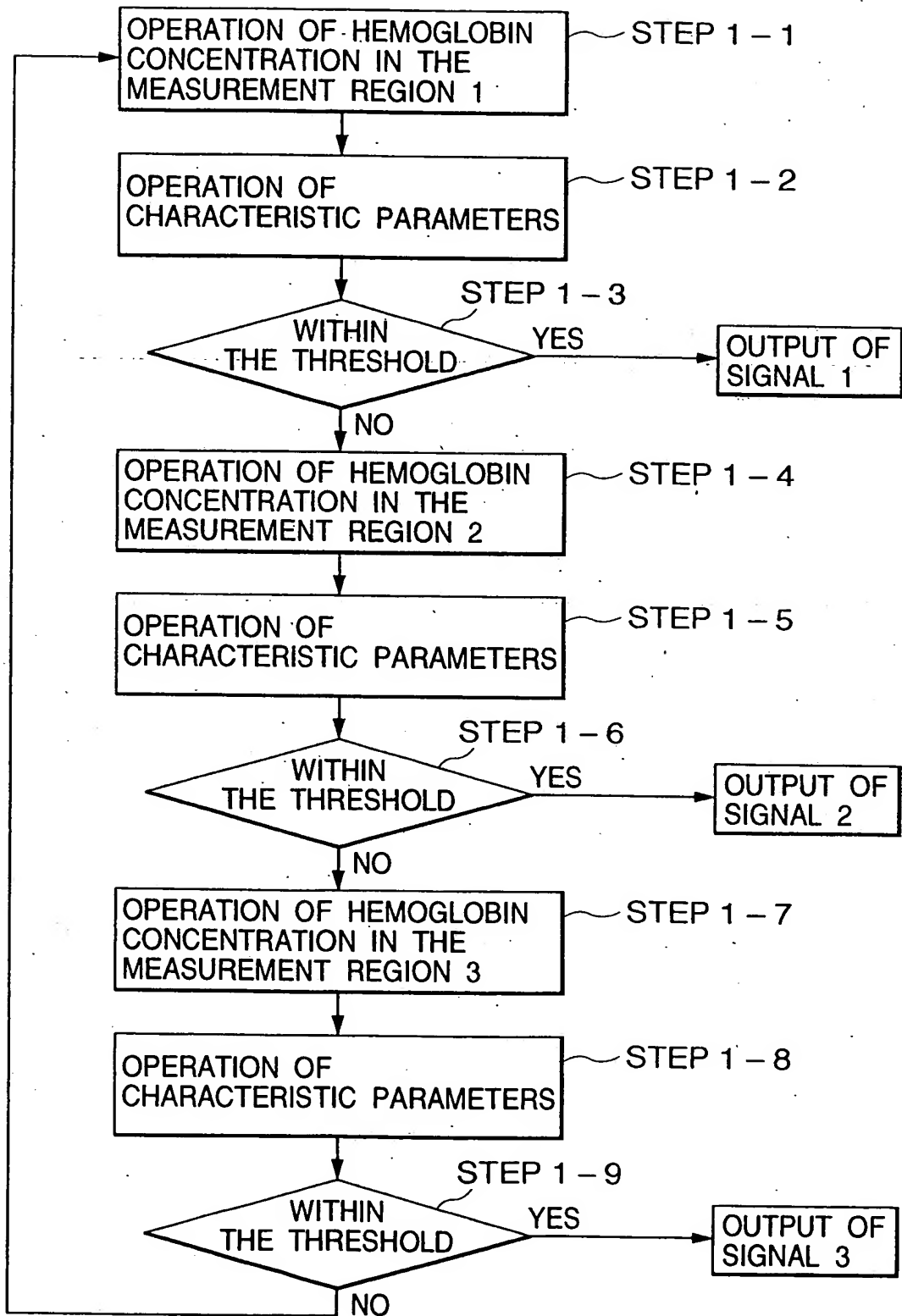


FIG. 35

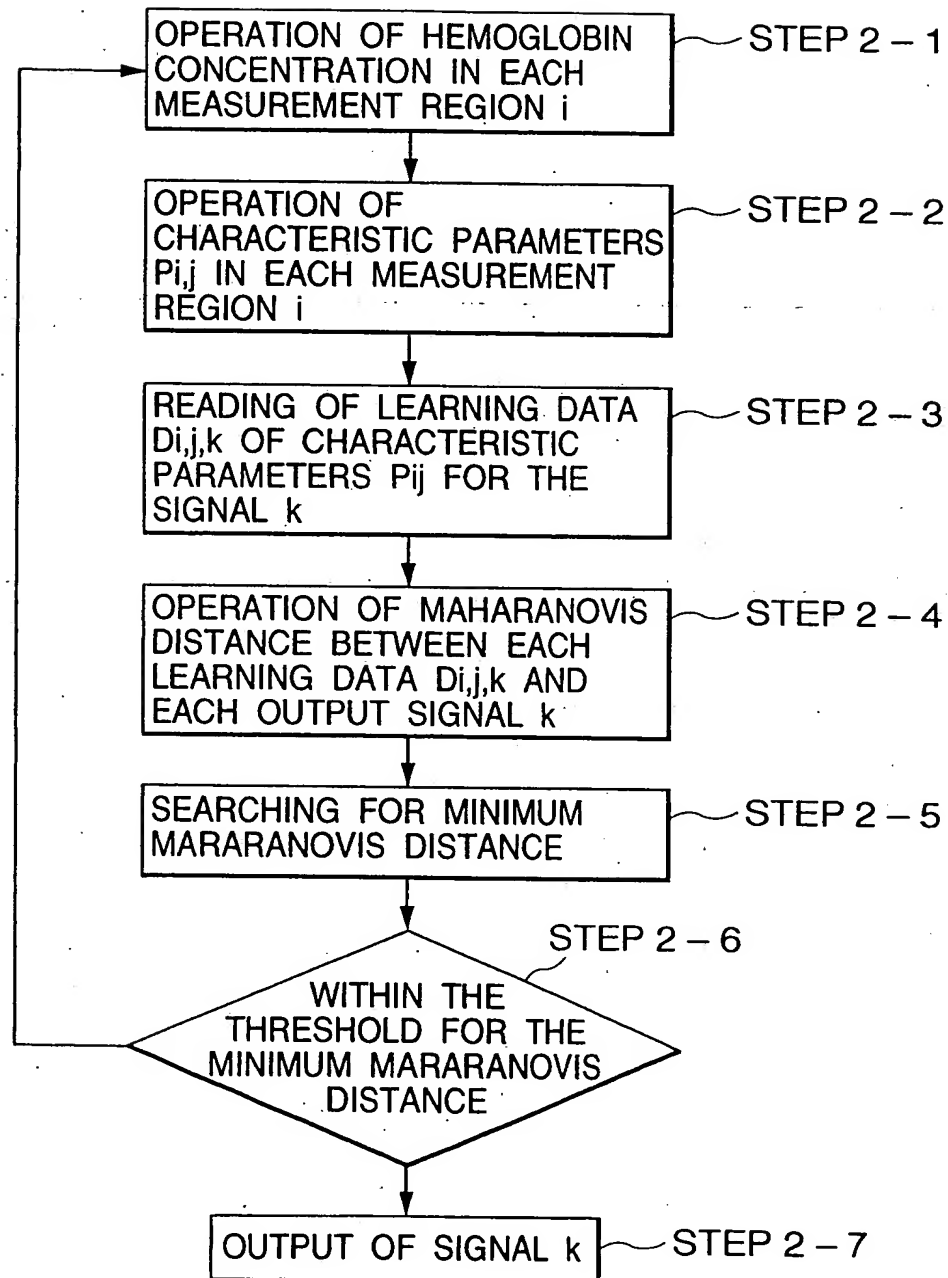


FIG. 36

<div> <div>CHARACTERISTIC PARAMETER j</div> <div>MESUREMENT REGION i</div> </div>	1	2	.....	m - 1	m
	1	2	.....	m - 1	m
1	$S_{1,1,k}$ $A_{1,1,k}$	$S_{1,2,k}$ $A_{1,2,k}$	.....	$S_{1,m-1,k}$ $A_{1,m-1,k}$	$S_{1,m,k}$ $A_{1,m,k}$
2	$S_{2,1,k}$ $A_{2,1,k}$	$S_{2,2,k}$ $A_{2,2,k}$	.....	$S_{2,m-1,k}$ $A_{2,m-1,k}$	$S_{2,m,k}$ $A_{2,m,k}$
⋮	⋮	⋮	⋮	⋮	⋮
n - 1	$S_{n-1,1,k}$ $A_{n-1,1,k}$	$S_{n-1,2,k}$ $A_{n-1,2,k}$	.....	$S_{n-1,m-1,k}$ $A_{n-1,m-1,k}$	$S_{n-1,m,k}$ $A_{n-1,m,k}$
n	$S_{n,1,k}$ $A_{n,1,k}$	$S_{n,2,k}$ $A_{n,2,k}$	.....	$S_{n,m-1,k}$ $A_{n,m-1,k}$	$S_{n,m,k}$ $A_{n,m,k}$



FIG. 37

